

R3G630-RB32-77

VERTIV S.R.L

EC centrifugal fan - RadiCal

backward-curved, single-intake

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Nominal data

Type	R3G630-RB32-77	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	1300
Power consumption	W	2700
Current draw	A	4.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	65.7	56.1	09 Power consumption P_{ed}	kW	2.73
02 Measurement category		A		09 Air flow q_v	m ³ /h	11235
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	543
04 Efficiency grade N		71.6	62	10 Speed (rpm) n	min ⁻¹	1295
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-175564



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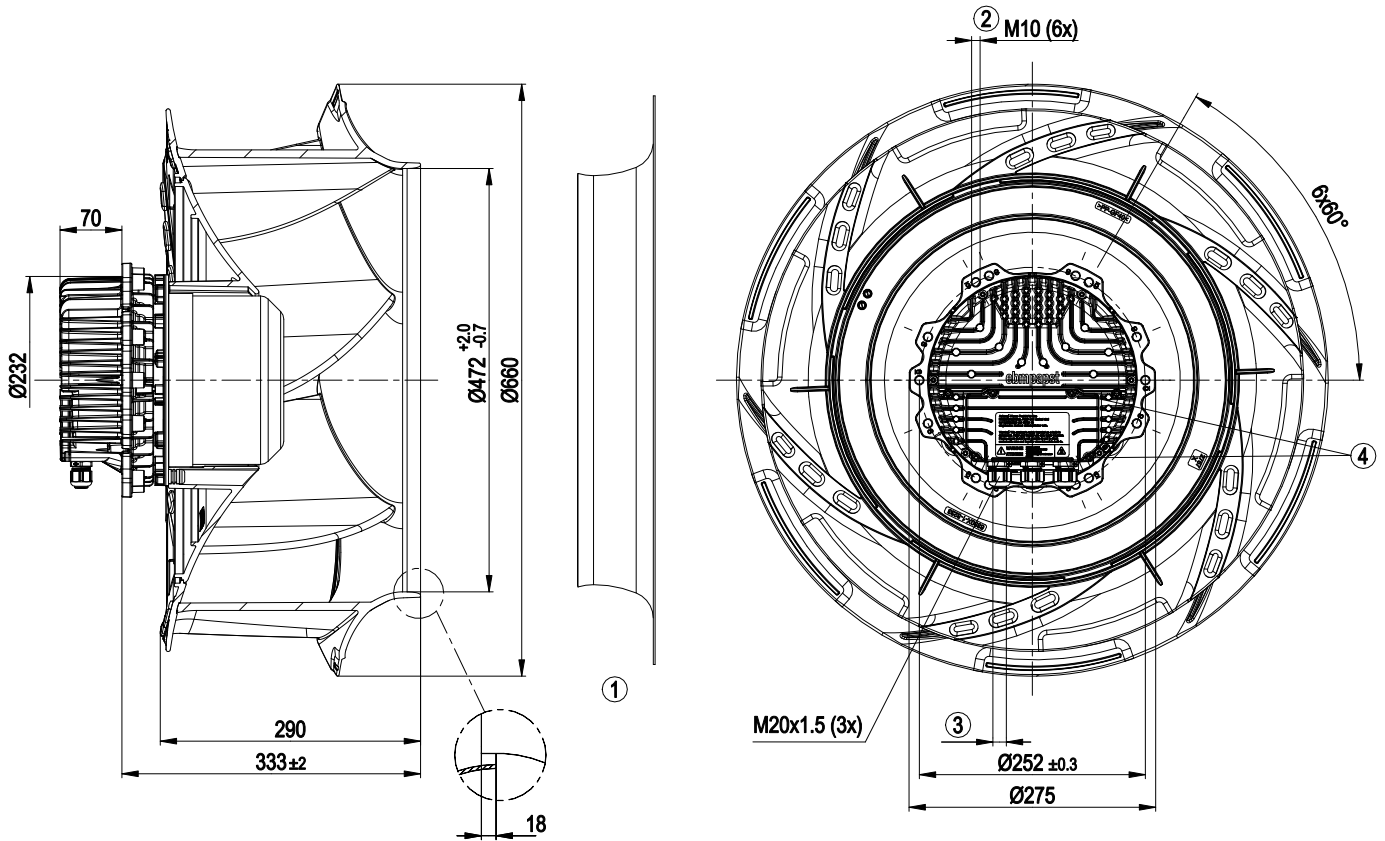
backward-curved, single-intake

Technical description

Weight	29 kg
Size	630 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Operation and alarm display - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

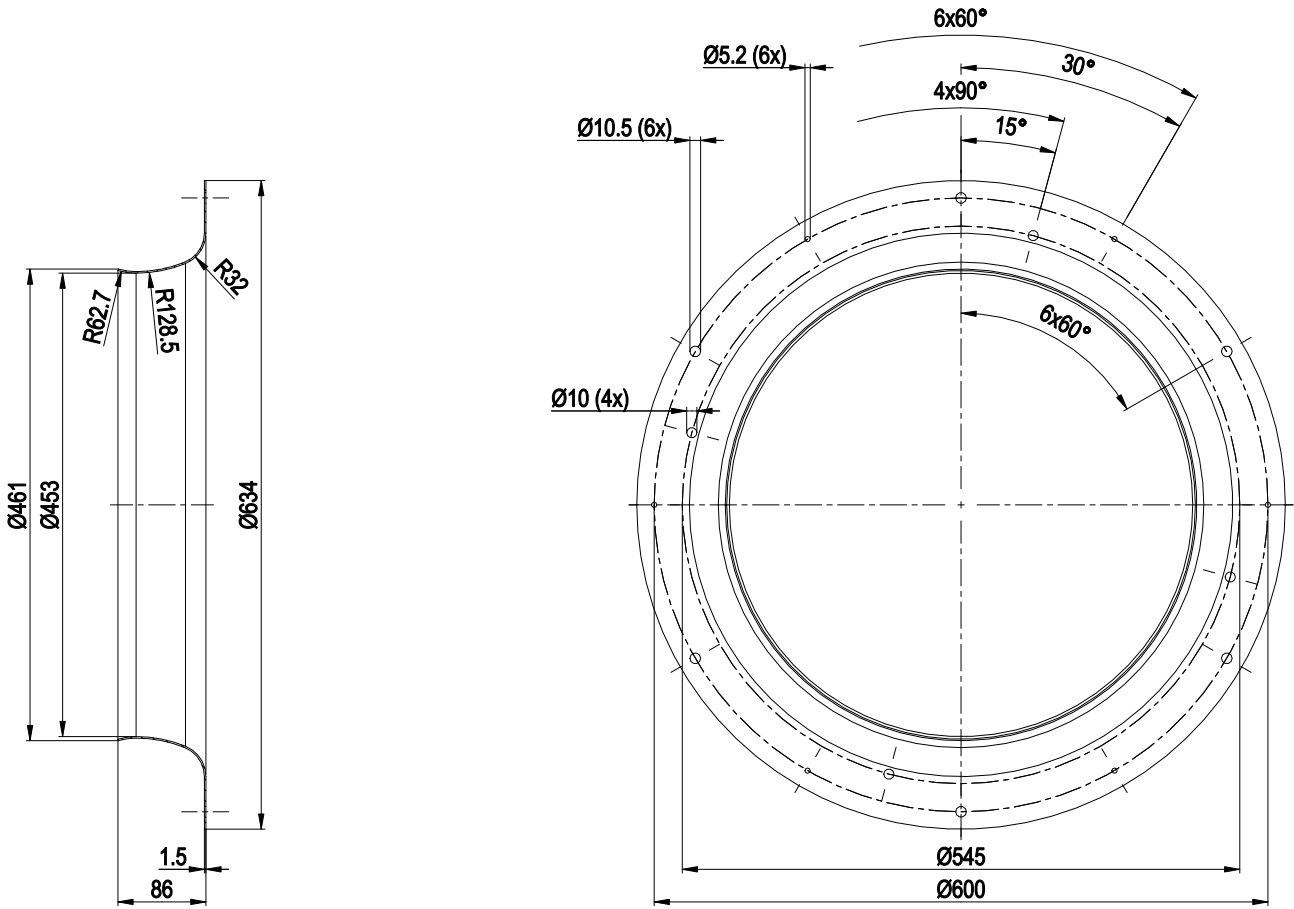


Product drawing



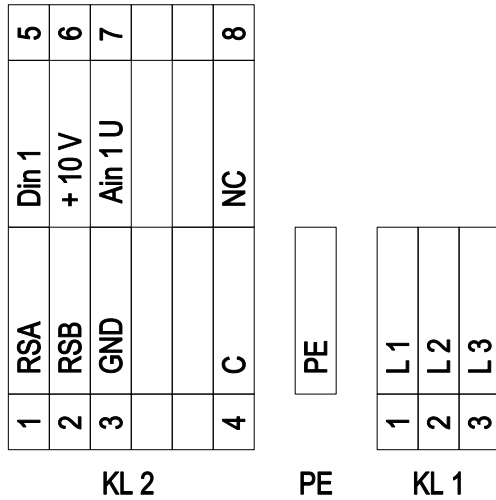
1	Accessory part: inlet ring 63300-2-4013 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

Accessory part



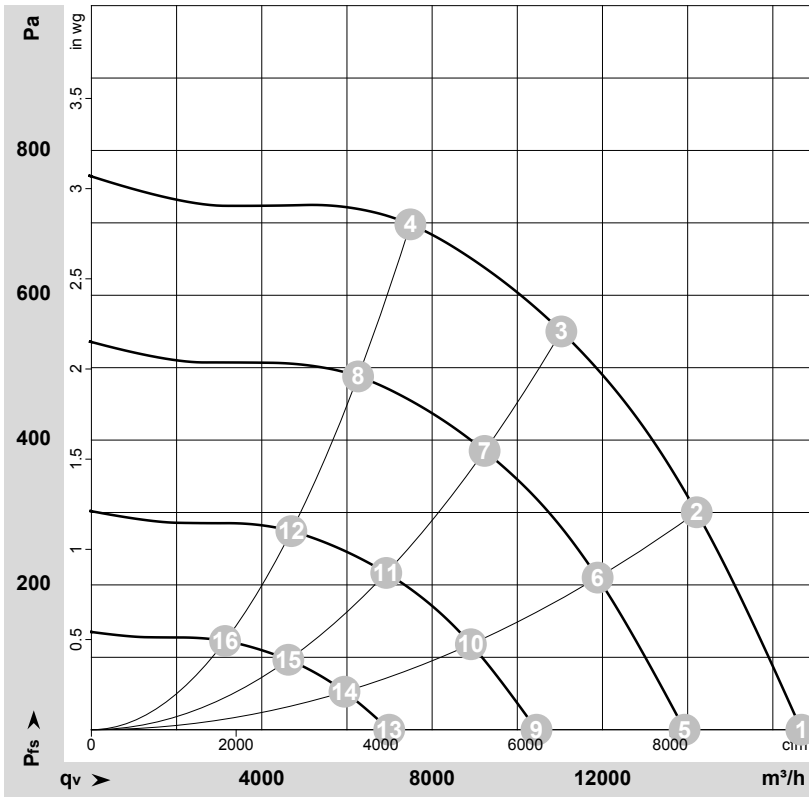
Inlet ring 63300-2-4013

Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 2	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 2	3	GND	Reference ground for control interface; SELV
KL2	4	C	Status relay, floating status contact, break for failure; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL 2	5	Din1	Digital input 1 enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV Or: +24 VDC input for parameter setting via MODBUS without line voltage
KL 2	7	Ain1 U	Analog input 1 (set value) 0-10 V, Ri = 100 kΩ, adjustable curve; SELV
KL2	8	NC	Status relay, floating status contact, break for failure

Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-175564-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	1300	1750	2.76	81	88	92	16670	0	9810	0.00
2	400	50	1300	2411	3.73	75	82	87	14210	300	8365	1.20
3	400	50	1300	2700	4.10	70	78	83	11035	550	6495	2.21
4	400	50	1300	2607	4.03	73	80	85	7490	700	4410	2.81
5	400	50	1085	1038	1.74	77	83	87	13930	0	8200	0.00
6	400	50	1085	1426	2.29	70	77	82	11885	213	6995	0.86
7	400	50	1085	1606	2.55	66	73	79	9230	386	5435	1.55
8	400	50	1085	1534	2.45	68	75	80	6260	491	3685	1.97
9	400	50	815	480	1.00	68	75	80	10450	0	6150	0.00
10	400	50	820	638	1.21	62	70	76	8910	120	5245	0.48
11	400	50	815	714	1.31	60	67	72	6925	217	4075	0.87
12	400	50	815	683	1.27	61	68	73	4695	276	2765	1.11
13	400	50	550	164	0.49	55	65	69	6995	0	4115	0.00
14	400	50	550	215	0.59	53	61	66	5940	53	3495	0.21
15	400	50	550	240	0.63	50	58	62	4625	97	2720	0.39
16	400	50	550	230	0.61	50	58	63	3140	123	1845	0.49

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase